

7. Riemannian curvature

Levi-Civita connection $\tilde{\Gamma}^r_{\alpha\beta} = \frac{1}{2} g^{rs} (\partial_s g_{\alpha\beta} + \partial_\beta g_{\alpha s} - \partial_\alpha g_{\beta s})$

Sometimes also called "Christoffel symbols."

Denote LC-covariant derivative as $\tilde{\nabla}_p T^r_v = \partial_p T^r_v + \tilde{\Gamma}^r_{\mu\alpha} T^\alpha_v - \tilde{\Gamma}^\alpha_{\mu\nu} T^\nu_\alpha$

Riemann curvature tensor: $[\tilde{\nabla}_\alpha, \tilde{\nabla}_\beta] V^r = \tilde{R}_{\alpha\beta}{}^r{}_v V^v - O \leftarrow \text{no torsion in the Levi-Civita connection!}$

General curvature tensor: $[\nabla_\alpha, \nabla_\beta] V^r = R_{\alpha\beta}{}^r{}_v V^v - T_{\alpha\beta}{}^\lambda \nabla_\lambda V^r$

Some properties of the curvature tensor:

$$\tilde{R}_{\alpha\beta}{}^r{}_v = \partial_\alpha \tilde{\Gamma}^r_{\beta v} - \partial_\beta \tilde{\Gamma}^r_{\alpha v} + \tilde{\Gamma}^r_{\alpha\lambda} \tilde{\Gamma}^\lambda_{\beta v} - \tilde{\Gamma}^r_{\beta\lambda} \tilde{\Gamma}^\lambda_{\alpha v}$$

$$\begin{aligned} \tilde{R}_{\alpha\beta\mu\nu} &= g_{\mu\rho} \tilde{R}_{\alpha\beta}{}^\rho{}_v \\ &= \partial_\alpha (g_{\mu\rho} \tilde{\Gamma}^\rho_{\beta v}) - \tilde{\Gamma}^\rho_{\beta v} (\partial_\alpha g_{\mu\rho}) - \partial_\beta (g_{\mu\rho} \tilde{\Gamma}^\rho_{\alpha v}) + \tilde{\Gamma}^\rho_{\alpha v} (\partial_\beta g_{\mu\rho}) \\ &\quad + \tilde{\Gamma}^\lambda_{\mu\alpha} \tilde{\Gamma}^\rho_{\lambda v} - \tilde{\Gamma}^\lambda_{\mu\lambda} \tilde{\Gamma}^\rho_{\alpha v} \\ &= \partial_\alpha \tilde{\Gamma}_{\mu\beta v} - \partial_\beta \tilde{\Gamma}_{\mu\alpha v} - \tilde{\Gamma}^\rho_{\mu v} \left(\overset{\circ}{\tilde{\Gamma}}_{\alpha\beta\rho} + \overset{\circ}{\tilde{\Gamma}}_{\beta\alpha\rho} \right) + \tilde{\Gamma}^\rho_{\mu v} \left(\overset{\circ}{\tilde{\Gamma}}_{\alpha\beta\rho} + \overset{\circ}{\tilde{\Gamma}}_{\beta\alpha\rho} \right) \\ &\quad + \tilde{\Gamma}^\lambda_{\mu\alpha} \tilde{\Gamma}^\rho_{\lambda v} - \tilde{\Gamma}^\lambda_{\mu\lambda} \tilde{\Gamma}^\rho_{\alpha v} \\ &= \partial_\alpha \tilde{\Gamma}_{\mu\beta v} - \partial_\beta \tilde{\Gamma}_{\mu\alpha v} + \tilde{\Gamma}^\lambda_{\alpha v} \tilde{\Gamma}_{\lambda\beta\mu} - \tilde{\Gamma}^\lambda_{\mu v} \tilde{\Gamma}_{\lambda\alpha\mu} \end{aligned}$$

(can check: $\tilde{R}_{\alpha\beta\mu\nu} = -\tilde{R}_{\beta\alpha\mu\nu}$ } two pairs of "antisymmetric" indices
 $\tilde{R}_{\alpha\beta\mu\nu} = -\tilde{R}_{\alpha\beta\nu\mu}$ } $[\alpha\beta]$ and $[\mu\nu]$

$$\tilde{R}_{\alpha[\beta\mu\nu]} = 0 \quad \rightarrow \text{Bianchi identity (found by Ricci)} \\ \Leftrightarrow \tilde{R}_{\alpha\beta\mu\nu} = \tilde{R}_{\mu\nu\alpha\beta} \wedge R_{[\mu\nu\alpha\beta]} = 0$$

\rightarrow # of independent components of $\tilde{R}_{\alpha\beta\mu\nu}$ is $\frac{n^2(n^2-1)}{12}$

General $R_{\alpha\beta\gamma\mu}$ with torsion: only have antisymmetry $\alpha \leftrightarrow \beta$ and $\gamma \leftrightarrow \nu$

$$\rightarrow \# = \frac{n^2(n-1)^2}{4}$$

Ricci tensor:

$$\tilde{R}_{\mu\nu} \equiv \tilde{R}_{\alpha\nu}{}^\alpha{}_\mu = \delta^\nu_\mu \tilde{R}_{\alpha\nu}{}^\alpha{}_\mu = \tilde{R}_{\alpha\nu}$$

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Ricci scalar:

$$\hat{R} = g^{\mu\nu} \tilde{R}_{\mu\nu}$$

Let's calculate the scalar curvature of a cylinder to prove it is flat!

$$g = dr \otimes dr + r^2 d\varphi \otimes d\varphi + dz \otimes dz \Big|_{r=\text{const.}} = r^2 d\varphi \otimes d\varphi + dz \otimes dz \quad \begin{matrix} \\ \text{constant!} \end{matrix}$$

$$\tilde{\Gamma}^\rho_{\alpha\beta} = \frac{1}{2} g^{\rho\lambda} (\partial_\alpha g_{\beta\lambda} + \partial_\beta g_{\alpha\lambda} - \partial_\lambda g_{\alpha\beta})$$

$$= 0 \quad \text{b/c } g_{\mu\nu} = \text{constant since } r = \text{constant!}$$

$$\Rightarrow \tilde{R}_{\alpha\beta}{}^\rho{}_\nu = 0 \quad \Rightarrow \text{cylinder is flat!}$$

Let's show that the scalar curvature of the 2-sphere is related to its radius!

$$g = dr \otimes dr + r^2 d\theta \otimes d\theta + r^2 \sin^2 \theta d\varphi \otimes d\varphi \Big|_{r=\text{const.}} = r^2 d\theta \otimes d\theta + r^2 \sin^2 \theta d\varphi \otimes d\varphi \quad \begin{matrix} \\ \text{r=constant!} \end{matrix}$$

$$\tilde{\Gamma}^\theta_{\theta\theta} = \frac{1}{2} g^{\theta\theta} (\partial_\theta g_{\theta\theta} + \partial_\theta g_{\theta\theta} - \partial_\theta g_{\theta\theta}) = 0$$

$$\tilde{\Gamma}^\theta_{\theta\varphi} = \frac{1}{2} g^{\theta\theta} (\partial_\theta g_{\theta\varphi} + \partial_\varphi g_{\theta\theta} - \partial_\theta g_{\varphi\theta}) = 0$$

$$\tilde{\Gamma}^\theta_{\varphi\varphi} = \frac{1}{2} g^{\theta\theta} (\partial_\varphi g_{\varphi\varphi} + \partial_\varphi g_{\varphi\varphi} - \partial_\varphi g_{\varphi\varphi}) = -\frac{1}{2} \frac{1}{r^2} r^2 2 \sin \theta \cos \theta = -\sin \theta \cos \theta$$

$$\tilde{\Gamma}^\varphi_{\theta\theta} = \frac{1}{2} g^{\varphi\varphi} (\partial_\theta g_{\theta\theta} + \partial_\theta g_{\theta\theta} - \partial_\theta g_{\theta\theta}) = 0$$

$$\tilde{\Gamma}^\varphi_{\theta\varphi} = \frac{1}{2} g^{\varphi\varphi} (\partial_\theta g_{\theta\varphi} + \partial_\varphi g_{\theta\theta} - \partial_\theta g_{\varphi\theta}) = \frac{1}{2} \frac{1}{r^2 \sin^2 \theta} r^2 2 \sin \theta \cos \theta = \frac{\cos \theta}{\sin \theta}$$

$$\tilde{\Gamma}^\varphi_{\varphi\varphi} = \frac{1}{2} g^{\varphi\varphi} (\partial_\varphi g_{\varphi\varphi} + \partial_\varphi g_{\varphi\varphi} - \partial_\varphi g_{\varphi\varphi}) = 0$$

→ only 2 non-zero $\tilde{\Gamma}^\rho_{\alpha\beta}$.

Next: calculate $\tilde{R}_{\alpha\beta}{}^\rho{}_\nu$

$$\tilde{R}_{\alpha\beta}{}^\lambda{}_\nu = \partial_\alpha \tilde{\Gamma}^\lambda{}_{\beta\nu} - \partial_\beta \tilde{\Gamma}^\lambda{}_{\alpha\nu} + \tilde{\Gamma}^\lambda{}_{\alpha\lambda} \tilde{\Gamma}^\lambda{}_{\beta\nu} - \tilde{\Gamma}^\lambda{}_{\beta\lambda} \tilde{\Gamma}^\lambda{}_{\alpha\nu}$$

We know there is only 1 component that matters b/c $\frac{n^2(n^2-1)}{12} = 1$ for $n=2$.

$$\begin{aligned}\tilde{R}_{\theta\varphi}{}^\theta{}_\varphi &= \partial_\theta \tilde{\Gamma}^\theta{}_{\varphi\varphi} - \partial_\varphi \tilde{\Gamma}^\theta{}_{\theta\varphi} + \tilde{\Gamma}^\theta{}_{\theta\lambda} \tilde{\Gamma}^\lambda{}_{\varphi\varphi} - \tilde{\Gamma}^\theta{}_{\varphi\lambda} \tilde{\Gamma}^\lambda{}_{\theta\varphi} \\ &= \partial_\theta \tilde{\Gamma}^\theta{}_{\varphi\varphi} - 0 + \underbrace{\tilde{\Gamma}^\theta{}_{\theta\theta} \tilde{\Gamma}^\theta{}_{\varphi\varphi}}_{=0} + \tilde{\Gamma}^\theta{}_{\theta\varphi} \underbrace{\tilde{\Gamma}^\varphi{}_{\varphi\varphi}}_{=0} - \underbrace{\tilde{\Gamma}^\theta{}_{\varphi\theta} \tilde{\Gamma}^\theta{}_{\theta\varphi}}_{=0} - \tilde{\Gamma}^\theta{}_{\varphi\varphi} \tilde{\Gamma}^\varphi{}_{\theta\varphi} \\ &= \partial_\theta (-\sin\theta \cos\theta) - (-\sin\theta \cos\theta) \left(\frac{\cos\theta}{\sin\theta}\right) \\ &= -\cos^2\theta + \sin^2\theta + \cos^2\theta = \sin^2\theta\end{aligned}$$

$$\tilde{R}_{\rho\nu} = \tilde{R}_{\alpha\rho}{}^\alpha{}_\nu = \tilde{R}_{\theta\rho}{}^\theta{}_\nu + \tilde{R}_{\varphi\rho}{}^\varphi{}_\nu$$

$$\begin{aligned}\tilde{R}_{\theta\theta} &= \tilde{R}_{\theta\theta}{}^\theta{}_\theta + \tilde{R}_{\varphi\theta}{}^\varphi{}_\theta = \tilde{R}_{\varphi\theta}{}^\varphi{}_\theta = -\tilde{R}_{\theta\varphi}{}^\varphi{}_\theta = -g^{\varphi\varphi} R_{\theta\varphi\varphi\theta} \\ &= +g^{\theta\theta} \tilde{R}_{\theta\varphi\theta\varphi} = g^{\theta\theta} g_{\theta\theta} \tilde{R}_{\theta\varphi}{}^\varphi{}_\theta = \frac{1}{r^2 \sin^2\theta} \cdot r^2 \cdot \sin^2\theta = 1\end{aligned}$$

$$\tilde{R}_{\theta\varphi} = \tilde{R}_{\alpha\theta}{}^\alpha{}_\varphi = \tilde{R}_{\theta\theta}{}^\theta{}_\varphi + \tilde{R}_{\varphi\theta}{}^\varphi{}_\varphi = 0$$

$$\tilde{R}_{\varphi\varphi} = \tilde{R}_{\alpha\varphi}{}^\alpha{}_\varphi = \tilde{R}_{\theta\varphi}{}^\theta{}_\varphi + \underbrace{\tilde{R}_{\varphi\varphi}{}^\varphi{}_\varphi}_{=0} = \sin^2\theta$$

$$\begin{aligned}\tilde{R} &= g^{\rho\nu} \tilde{R}_{\rho\nu} = g^{\theta\theta} \tilde{R}_{\theta\theta} + \underbrace{g^{\theta\varphi} \tilde{R}_{\theta\varphi}}_0 + \underbrace{g^{\varphi\theta} \tilde{R}_{\varphi\theta}}_0 + g^{\varphi\varphi} \tilde{R}_{\varphi\varphi} \\ &= \frac{1}{r^2} + \frac{1}{r^2 \sin^2\theta} \sin^2\theta = \frac{2}{r^2}\end{aligned}$$

→ final result: $\boxed{\tilde{R} = \frac{2}{r^2}}$

Scalar curvature of a sphere is given by its inverse radius squared!