

3. Coordinates + coordinate transformations

Recap:
$$\underline{T} = \underbrace{T^i_j \hat{e}_i}_{\text{abstract basis}} \otimes \underbrace{\hat{\theta}^j}_{\text{coordinate basis}} = T^{\mu}_{\nu} \frac{\partial}{\partial x^{\mu}} \otimes dx^{\nu}$$

$$\left[\begin{array}{l} \hat{e}_i = e^{\mu}_i \frac{\partial}{\partial x^{\mu}} \quad , \quad \hat{\theta}^j = e^j_{\nu} dx^{\nu} \\ \Leftrightarrow \frac{\partial}{\partial x^{\mu}} = e^i_{\mu} \hat{e}_i \quad , \quad dx^{\nu} = e^{\nu}_j \hat{\theta}^j \end{array} \right. \left. \vphantom{\frac{\partial}{\partial x^{\mu}}} \right\} \text{relation between bases}$$

$$\left[\begin{array}{l} T^{\mu}_{\nu} = e^{\mu}_i e^j_{\nu} T^i_j \quad \Leftrightarrow \quad T^i_j = e^i_{\mu} e^{\nu}_j T^{\mu}_{\nu} \\ \text{relation between tensor components} \end{array} \right.$$

Basis and cobasis are always dual: $\hat{e}_i \lrcorner \hat{\theta}^j = \delta_i^j$ and $\frac{\partial}{\partial x^{\mu}} \lrcorner dx^{\nu} = \delta_{\mu}^{\nu}$

This implies $e^{\mu}_i e^j_{\mu} = \delta_i^j$ and $e^i_{\mu} e^{\nu}_i = \delta_{\mu}^{\nu}$.

Now: let us focus a bit on coordinates!

Notation: $x^{\mu} = (x, y, z)$ or $x^{\mu} = (r, \theta, \varphi)$ μ numbers the coordinates.
 $x^x = x, x^y = y, x^z = z$ $x^r = r, x^{\theta} = \theta, x^{\varphi} = \varphi$ (looks a bit confusing)

e.g. $\underline{\eta} = \underbrace{dx \otimes dx + dy \otimes dy + dz \otimes dz}_{\text{this is } \eta_{xx}} = \eta_{\mu\nu} dx^{\mu} \otimes dx^{\nu}$

e.g. $\underline{v} = x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \equiv x \partial_y - y \partial_x = v^{\mu} \frac{\partial}{\partial x^{\mu}} \equiv v^{\mu} \partial_{\mu}$
 $= v^x \partial_x + v^y \partial_y \rightarrow v^x = -y, v^y = x$

e.g. $\underline{M} = 24z \begin{matrix} \partial_x \otimes dz \\ \partial_r \otimes dx^{\nu} \end{matrix} = M^{\mu}_{\nu} \partial_{\mu} \otimes dx^{\nu}$
 $\mu=x \quad \nu=z \rightarrow M^x_z = 24z$

Coordinate transformations:

$$X^{\mu} = (x, y, z) \rightarrow y^{\nu'} = (r, \theta, \varphi)$$

$r = x, y, z$ new symbol new index $\nu' = r, \theta, \varphi$

Know how coordinate (co-)basis transforms; chain rule!

$$\frac{\partial}{\partial x^{\mu}} = \frac{\partial y^{\nu'}}{\partial x^{\mu}} \frac{\partial}{\partial y^{\nu'}} \quad , \quad dx^{\mu} = \frac{\partial x^{\mu}}{\partial y^{\nu'}} dy^{\nu'}$$

What about tensors? E.g. (1) tensor \underline{I} ?

Must have: $\underline{I} = T^{\mu}_{\nu} \frac{\partial}{\partial x^{\mu}} \otimes dx^{\nu} = T^{\mu'}_{\nu'} \frac{\partial}{\partial y^{\mu'}} \otimes dy^{\nu'}$

Remember: a tensor \underline{I} is a geometric object that can be described by any basis!

Question: what's the relation between T^{μ}_{ν} and $T^{\mu'}_{\nu'}$?

$$\begin{aligned} T^{\mu'}_{\nu'} \frac{\partial}{\partial y^{\mu'}} \otimes dy^{\nu'} &= T^{\mu'}_{\nu'} \frac{\partial x^{\mu}}{\partial y^{\mu'}} \frac{\partial}{\partial x^{\mu}} \otimes \frac{\partial y^{\nu'}}{\partial x^{\nu}} dx^{\nu} \\ &= \underbrace{T^{\mu'}_{\nu'} \frac{\partial x^{\mu}}{\partial y^{\mu'}} \frac{\partial y^{\nu'}}{\partial x^{\nu}}}_{\equiv T^{\mu}_{\nu}} \frac{\partial}{\partial x^{\mu}} \otimes dx^{\nu} \end{aligned}$$

$$\left. \begin{aligned} \rightarrow T^{\mu}_{\nu} &= \frac{\partial x^{\mu}}{\partial y^{\mu'}} \frac{\partial y^{\nu'}}{\partial x^{\nu}} T^{\mu'}_{\nu'} \\ \rightarrow T^{\mu'}_{\nu'} &= \frac{\partial y^{\mu'}}{\partial x^{\mu}} \frac{\partial x^{\nu}}{\partial y^{\nu'}} T^{\mu}_{\nu} \end{aligned} \right\} \text{use: } \frac{\partial x^{\mu}}{\partial y^{\mu'}} \frac{\partial y^{\nu'}}{\partial x^{\nu}} = \delta^{\mu}_{\nu}$$

Quick & easy way to compute tensors in a new basis: forget about indices!

Transforming $\underline{v} = x \partial_y - y \partial_x$ to (r, φ) -coordinates is easier the following way:

$$\begin{aligned} x = r \cos \varphi & \quad \frac{\partial r}{\partial x} = \cos \varphi & \quad \frac{\partial \varphi}{\partial x} = \frac{-\sin \varphi}{r} & \quad x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} = x \left(\frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \varphi}{\partial y} \frac{\partial}{\partial \varphi} \right) \\ y = r \sin \varphi & \quad \frac{\partial r}{\partial y} = \sin \varphi & \quad \frac{\partial \varphi}{\partial y} = \frac{\cos \varphi}{r} & \quad - y \left(\frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \varphi}{\partial x} \frac{\partial}{\partial \varphi} \right) \\ & & & \quad = \dots = \partial / \partial r = \partial_r \end{aligned}$$